

30th Conference Vibrations in Physical Systems – VIBSYS 2022 September 26-28, 2022, Poznań, Poland

Synchronization and Energy Transfer in 4DoF Friction-Induced Self- and Parametrically Excited Oscillators

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Presentation Plan

1. Introduction

- Innovativeness

2. System Model

- Derived Equations of motion
- Investigation scenarios -

3. Discussion of Scientific Results

- 4. Conclusion
- **5.** References
- 6. Acknowledgement





Introduction

A phenomenon where oscillators with different frequencies adjust their rhythms to oscillate in unison. The coupling is responsible for the flow of energy between them.



Synchronization and Energy Transfer in 4DoF Friction-Induced Self- and Parametrically Excited Oscillators

Oscillations are driven by varying some parameter(s) at some frequenc(y/ies), typically different from the natural frequency



Present in mechanical/ electromechanical devices where rubbing surfaces introduce some kinds of energies (negative damping) into the oscillating unit.



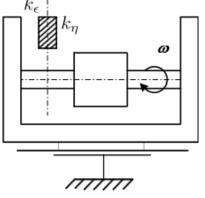


Other works VS Innovativeness

Phenomenon such as vibration quenching, anti-resonance, and synchronization have been studied by Authors such as Warmiński, Litak, Dohnal and Ecker in [1-3], and simultaneously occurring parametric and self excited vibrations by Tondl, Szabelski and Warmiński [5-8]. However, their study is limited to continuous/2DoF systems. We are studying this phenomena in discontinuous system

- The system under study is an expansion of the model in [4]*, it models a caliper mass and stiffness, with parametric excitation provided by unbalanced rotating parts.
- > Found in deep drilling, and automobile brake system

[4] Awrejcewicz, et al "Asymptotic Approaches in Nonlinear Dynamics," Springer ,1998









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System model:

- > A 4DoF electromechanical system (Fig. 2) with frame M_1 placed of moving belt with constant velocity v_0
- > The frame encloses a weightless shaft with rectangular cross-section, and a cylinder-like mass m_1 concentrated at the center
- > M_1 is coupled to another mass m_4 , placed on a frictionless surface, using a linear coupling spring of stiffness k_c

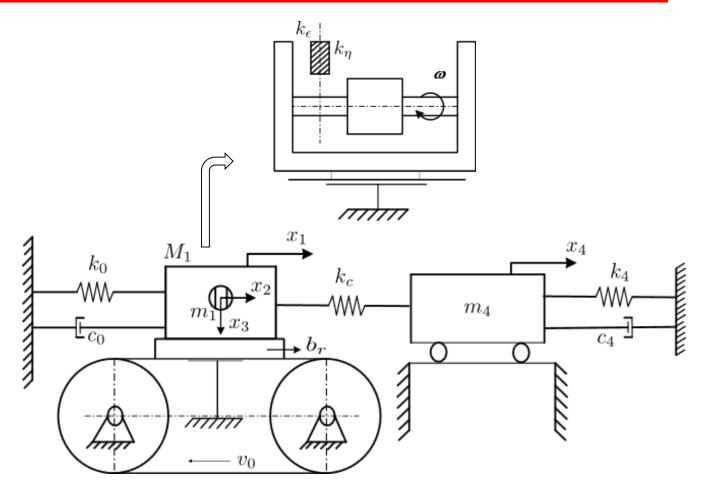


Fig. 2: Model of rotor with parametric excitation placed on friction-induced self-excited support, connected to a supplementary degree of freedom



Derived Equations of Motion

In nondimensional form

 $\ddot{X}_{1} = -X_{1}(A_{0} + \eta_{2}d + \eta_{1}b_{1} + \eta_{1}b_{2}\cos(2\gamma\tau))\gamma^{2} + X_{2}(\eta_{1}b_{1} + \eta_{1}b_{2}\cos(2\gamma\tau))\gamma^{2} - X_{3}(\eta_{1}b_{2}\gamma^{2}\sin(2\gamma\tau)) + (1)$ $X_{4}\eta_{2}d\gamma^{2} - \dot{X}_{1}h_{1}\gamma + [X_{1}(\eta_{1}b_{2}\gamma^{2}\sin(2\gamma\tau)) - X_{2}(\eta_{1}b_{2}\gamma^{2}\sin(2\gamma\tau)) + X_{3}(\eta_{1}b_{1} - \eta_{1}b_{2}\cos(2\gamma\tau))\gamma^{2} + 1]b_{r}$

$$\ddot{X}_2 = X_1(b_1 + b_2\cos(2\gamma\tau))\gamma^2 - X_2(b_1 + b_2\cos(2\gamma\tau))\gamma^2 + X_3(b_2\gamma^2\sin(2\gamma\tau)) + \kappa\gamma^2\sin(\gamma\tau + \phi_0)$$
(2)

$$\ddot{X}_3 = -X_1(b_2\gamma^2\sin(2\gamma\tau)) + X_2(b_2\gamma^2\sin(2\gamma\tau)) - X_3(b_1\gamma^2 - b_2\gamma^2\cos(2\gamma\tau)) + \kappa\gamma^2\cos(\gamma\tau + \phi_0) + 1$$
(3)

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 $\ddot{X}_4 = X_1 d\gamma^2 - X_4 - \dot{X}_4 h_4 \gamma$

State space variables: $(y_1, v_1, y_2, v_2, y_3, v_3, y_4, v_4)$

6

(4)



Power/Energy Balance Equation

$$\dot{X}_{1}\ddot{X}_{1} + \dot{X}_{1}X_{1}A_{0}\gamma^{2} + \dot{X}_{1}\eta_{2}d\gamma^{2}(X_{1} - X_{4}) + \dot{X}_{1}\dot{X}_{1}h_{1}\gamma = \dot{X}_{2}F_{pe} + \dot{X}_{1}F_{br}$$

$$\dot{X}_{4}\ddot{X}_{4} - \dot{X}_{4}X_{1}d\gamma^{2} + \dot{X}_{4}X_{4} + \dot{X}_{4}\dot{X}_{4}h_{4}\gamma = 0$$
(5)
(6)

where

$$F_{pe} = -X_1(\eta_1 b_1 + \eta_1 b_2 \cos(2\gamma\tau))\gamma^2 + X_2(\eta_1 b_1 + \eta_1 b_2 \cos(2\gamma\tau))\gamma^2 - X_3(\eta_1 b_2 \gamma^2 \sin(2\gamma\tau))$$
(7)

$$F_{br} = (X_1(\eta_1 b_2 \gamma^2 \sin(2\gamma \tau)) - X_2(\eta_1 b_2 \gamma^2 \sin(2\gamma \tau)) + X_3(\eta_1 b_1 - \eta_1 b_2 \cos(2\gamma \tau))\gamma^2 + 1)b_r$$
(8)

With ref to the work of Kulke and Ostermeyer in [9]

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Investigation scenarios and parameters

Table 1: Simulation parameters

	$\varphi_0 = \frac{4}{2}$			
	= 1.92			
	Data Sets			*Primary Set: DS1
	Parameter	Data Set 1 (DS1)	Data Set 2 (DS2)	Secondary: DS2,
	b_1	177.5148	710.0592	
	b_2	5.3184	8.1462	
	d	22.1893	44.3787	
log	<i>A</i> ₀	33.2840	532.5444	

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Discussion of Scientific results

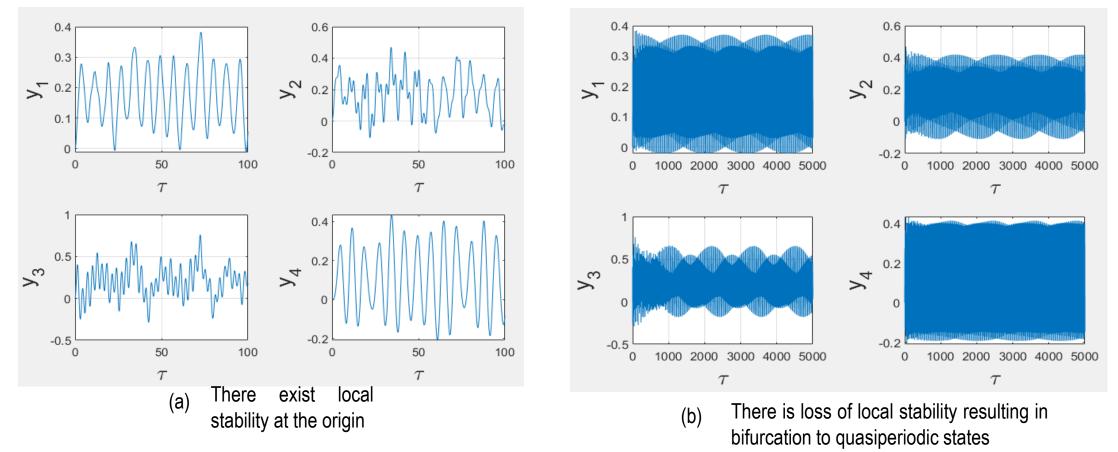


Fig. 3: Nonlinear dynamical responses to initial conditions [0,0,0,0,0,0,0,0], on DS1 with (a) Equilibrium states at the origin, (b) Hopf (secondary) bifurcation to quasiperiodic states in finite time τ





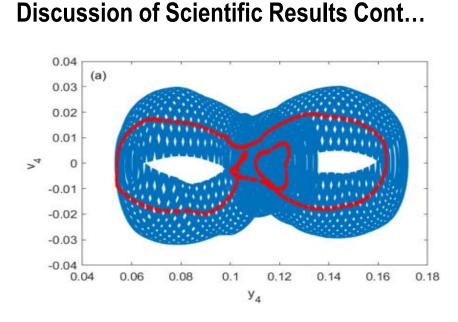
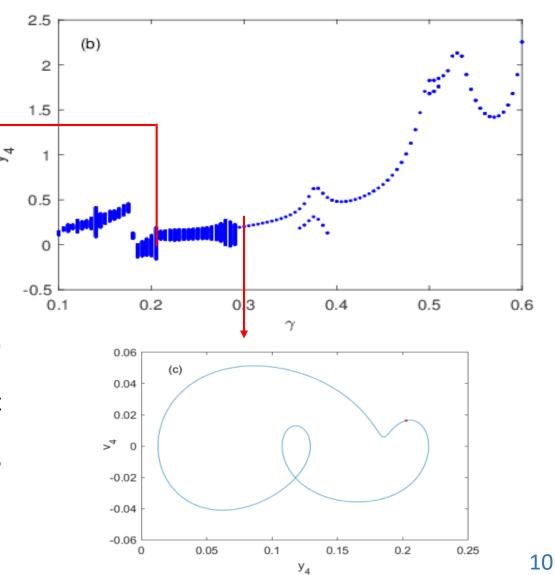
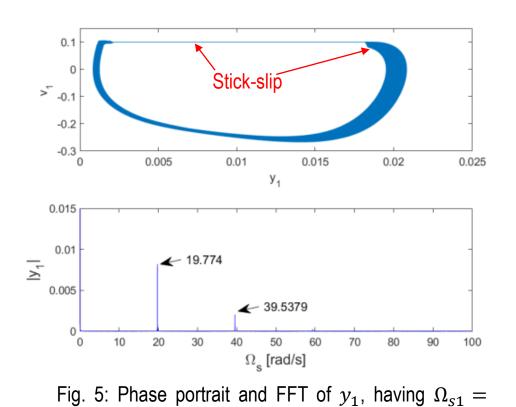


Fig. 4: Secondary Hopf (Niemark-Sacker) bifurcation scenario with phase portrait and Poincare section showing the existence of limit cycles (a)[$\gamma = 0.22$], in the bifurcation diagram (b), and destruction of the limit cycles to periodic states in (c) [$\gamma = 0.3$], with respect to structure m_4





Discussion of Scientific Results Cont...



Synchronization phenomenon

...from mutual interaction between self- and parametric excitations

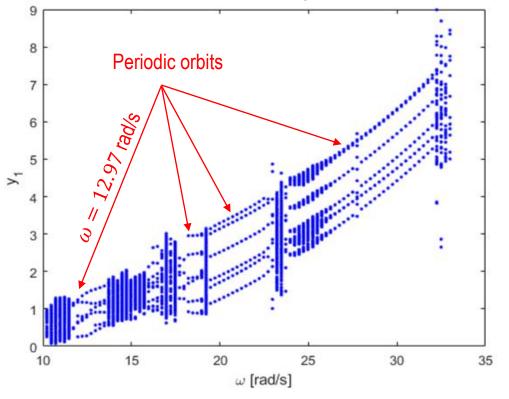


Fig. 6: Bifurcation diagram w.r.t y_1 using parametric frequency ω as the control parameter



19.77 *rad/s*



Discussion of Scientific Results Cont...

Synchronization phenomenon...

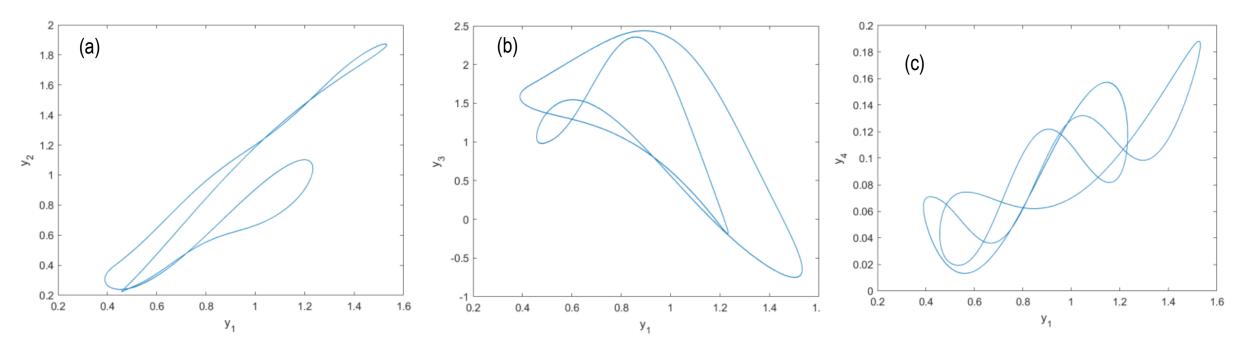


Fig. 7: Lissajous plot of mass M_1 with other oscillators at $\omega = 12.97$ rad/sec. Closed curves in all plots show synchronization in the system for (a) (y_1, y_2) , (b) (y_1, y_3) , (a) (y_1, y_4)





Discussion of Scientific Results Cont...

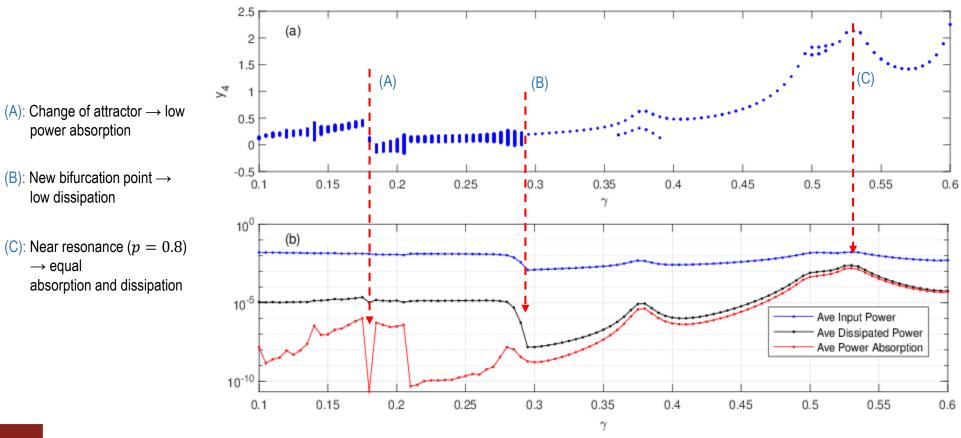


Fig. 8: Energy transfer relations of m_4 w.r.t v on DS1

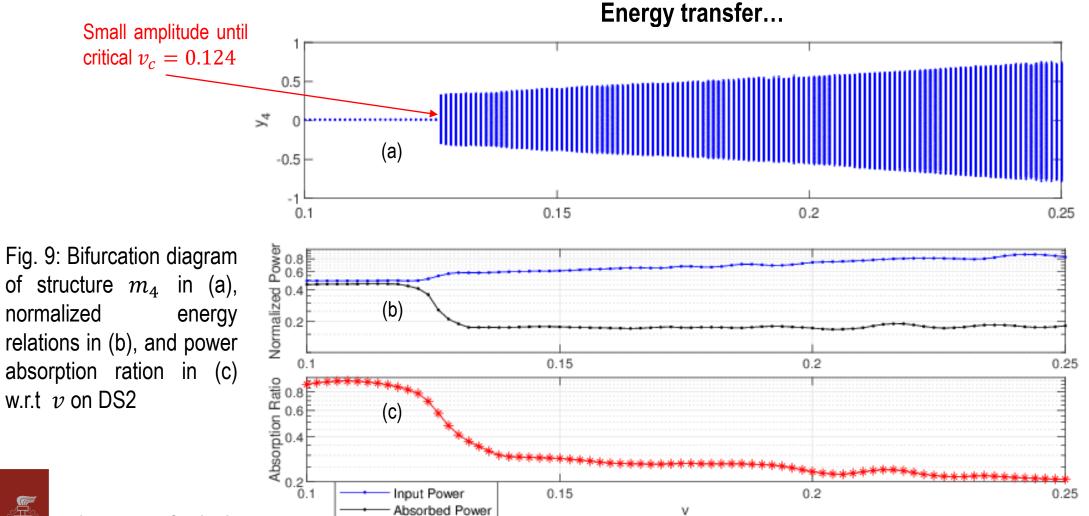
Energy transfer



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Conclusion

- There is mutual interaction between friction-induced self-excitation and parametric excitation leading to some phenomena such as synchronization-to-periodic-orbits, Neimark-Sacker bifurcation, small-amplitude vibration, and energy transfer in the system
- > Lissajous curves show the complex synchronization patterns for all harmonics in the system
- Presence of changing attractors (bifurcation points) are reflected in the energy balance mechanism of the system
- > Practical applications involves energy harvesting, automobile braking system, deep drilling, etc.





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Acknowledgement

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Thank you for your kind attention!

