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**SMALL δ METHOD APPLIED FOR CONSTRUCTION OF PERIODIC
SOLUTIONS TO NONLINEAR PARTIAL DIFFERENTIAL EQUATIONS**

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Summary. A non-linear wave equation with Dirichlet boundary conditions is analysed. A so called small δ method is applied. It has been shown, among others that a "problem of small denominators" is omitted using the introduced approach.

1. Introduction

A problem of construction of periodic solutions to non-linear partial differential equations has attracted recently an attention of many researchers [1-21]. Some of possible approaches in a frame of quasi-linear technics have been presented in various monographs. Among others we must mention the KAM (Kolmogorov-Arnol'd-Moser) - theory [15-18], averaging method [9, 11], renormalization approach with an introduction of artificial small parameter [19, 20], multi-scale approach [10].

The problems concerning the existence of periodic solutions have been considered in references [1, 2, 9, 12-18]. In reference [13] the variational technique is used, which will be briefly sketched. Consider the following problem

$$u_{tt} = u_{xx} + f(u), \quad 0 < x < \pi, \quad (1)$$

$$u(0,t) = u(\pi,t) = 0. \quad (2)$$

Under certain (fairly weak) conditions of the nonlinear term $f(u)$, the existence of the periodic solution

$$u(x, t) = u(x, t + T), \quad T = \gamma\pi \quad (3)$$

is proved, where γ is the rational number. The last requirement refers to the approach used in the reference [13]. A review of the papers using the variational techniques is presented in reference [14].

An application of the KAM - theory allowed to examine a case of irrational γ occurred in (3) [12, 15-18]. In particular, in references [15, 16] the existence of time periodical solutions of the boundary value problems (1), (2) with $f(u) = \nu u + u^3$ and with fixed γ in (3) has been shown. A generalization of the technique presented in [15, 16] has been proposed in investigations [17, 18]. The variational approach and KAM - theory are complementary to one another and allow to cover a whole interval of frequencies (in the case of proof of existence of solutions). A construction of periodic solutions in time of non-linear partial differential equations is outlined in references [3-11, 19, 20].

The fundamental problem occurring during a formal construction of periodic solutions in all earlier discussed cases is related to that of small denominators. The mentioned problem can be briefly presented in the following manner. Suppose that a time periodic solution is constructed to the following boundary value problem

$$u_{tt} = u_{xx} + \varepsilon u^3, \quad \varepsilon \ll 1, \quad (4)$$

$$u(0, t) = u(\pi, t) = 0. \quad (5)$$

Using a first approximation one obtains a linear wave equation. In order to get higher approximations one needs to insert a linear wave operator. The last operation leads to an occurrence of small denominators.

Therefore, a natural need for finding another parameter of asymptotic series to avoid the mentioned drawbacks is required. In the papers [22, 23] the so called "small δ method" is proposed, which relies on introduction of artificial "small parameter" δ in a power of non-linear terms.

According to that approach equation (4) should be rewritten to the form

$$u_{tt} = u_{xx} + \varepsilon u^{1+2\delta},$$

and its solution can be sought in the series form of small parameter δ .

An application of the outlined procedure to a series of nonlinear equations showed its high effectivity.

2. One dimensional space problem

Let us consider the equation

$$u_{tt} = u_{xx} - (\omega^2 - 1)u^3 \quad (6)$$

with the Dirichlet boundary conditions

$$u(0, t) = u(\pi, t) = 0. \quad (7)$$

We take $\omega^2 = \text{const}$, $1 < \omega^2 < \infty$.

From a physical point of view the boundary problem (6), (7) describes a longitudinal bar vibrations in non-linear elastic medium.

We introduce a small parameter in the following way

$$u_{tt} = u_{xx} - (\omega^2 - 1)u^{1+2\delta} \quad (8)$$

A solution to the boundary value problem (8), (7) has the form

$$u = u_0 + \delta u_1 + \delta^2 u_2 + \dots \quad (9)$$

The time variable t is changed according to Poincaré-Lindstedt method

$$t = \tau / \omega, \quad (10)$$

$$\omega^2 = 1 + \alpha_1 \delta + \alpha_2 \delta^2 + \dots \quad (11)$$

After introducing of (9) - (11) to the boundary value problem (7), (8) and splitting in regard to δ the following recurrent system of equations is obtained

$$u_{0\tau\tau} = u_{0xx} - (\omega^2 - 1)u_0, \quad (12)$$

$$u_{1\tau\tau} + \alpha_1 u_{0\tau\tau} = u_{1xx} - (\omega^2 - 1)u_1 - (\omega^2 - 1)u_0 \ln(u_0^2), \quad (13)$$

$$u_{2\tau\tau} + \alpha_2 u_{0\tau\tau} + \alpha_1 u_{1\tau\tau} = u_{2xx} - (\omega^2 - 1)u_2 - (\omega^2 - 1)\{u_1 \ln(u_0^2) + 2u_1 + 0.5u_0[\ln(u_0^2)]^2\}, \quad (14)$$

$$u_i(0, t) = u_i(\pi, t) = 0, \quad i = 0, 1, 2, \dots \quad (15)$$

We are going to find a periodic solution to the boundary value problem (7), (8) taking into account the following initial conditions

$$u(x,0) = \sin x; \quad (16)$$

$$u_t(x,0) = 0. \quad (17)$$

In order to satisfy the initial conditions (16), (17) two different approaches might be applied. One of them is related to a series development of initial conditions in regard to δ . Thus, we get in each of the approximation (excluding zero order solution) the homogeneous boundary conditions. In the second approach a zero order solution is obtained with an accuracy of an arbitrary constant, which is then defined by a final solution. This approach represents a kind of renormalization method and seems to be more suitable for our purpose.

Let us take a zero order solution of (12), (15)-(17) in the form

$$u_0 = A \sin x \cos(\omega\tau),$$

where the constant A will be further defined.

The first order solution has the form

$$u_{1,\tau\tau} - u_{1,xx} + (\omega^2 - 1)u_1 = L \equiv A \sin x \cos(\omega\tau) \{ \alpha_1 \omega^2 + \ln A - (\omega^2 - 1)[\ln(\sin^2 x) + \ln(\cos^2(\omega\tau))] \}. \quad (18)$$

The constant α_1 is found using a condition of avoiding a secular term:

$$\int_0^{\pi/2} \int_0^{\pi/(2\omega)} L \sin x \cos(\omega\tau) dx d\tau = 0$$

which yields

$$\alpha_1 = -\frac{\ln A}{\omega^2} - \frac{\omega^2 - 1}{2\omega^2} (2 \ln 2 - 1)(1 + \omega).$$

Now the functions $\sin x \ln(\sin^2 x)$ and $\cos(\omega\tau) \ln(\cos^2 \omega\tau)$ are developed into the Fourier series, and L reads

$$L = -A(\omega^2 - 1) \left[\sin x \sum_{j=2}^{\infty} T_j \cos(j\omega\tau) + \cos(\omega\tau) \sum_{k=2}^{\infty} X_k \sin kx \right], \quad (19)$$

where:

$$T_j = -\frac{4}{j^2 - 1}, \quad j = 3, 5, 7, \dots$$

$$X_k = -\frac{4}{k^2 - 1}, \quad k = 3, 5, 7, \dots$$
(20)

The particular solution of (18) can be presented in the form

$$u^{(1)} = u^{(11)} + u^{(12)}; \quad (21)$$

where:

$$u^{(11)} = A(\omega^2 - 1) \sin x \sum_{j=2}^{\infty} T_j^{(1)} \cos(j\omega\tau),$$

$$u^{(12)} = -A(\omega^2 - 1) \sin(\omega\tau) \sum_{j=2}^{\infty} X_k^{(1)} \sin kx, \quad (22)$$

$$T_j^{(1)} = \frac{T_j}{\omega^2(j^2 - 1)}; \quad X_k^{(1)} = \frac{1}{k^2 - 1}.$$

The function $u^{(1)}$ satisfies the initial condition (17). The function $u^{(11)}$ gives a condition to define the constant A in this approximation

$$u_0 + \delta u^{(11)} = 1$$

Therefore

$$1 = A + A\delta(\omega^2 - 1) \sum_{j=2}^{\infty} T_j^{(1)}. \quad (23)$$

In order to compensate residual function in the initial condition (16) introduced by the function $u^{(12)}$ it is necessary to modify a general solution of a homogeneous equation of the first order approximation

$$u_{\tau\tau}^{(2)} - u_{xx}^{(2)} + (\omega^2 - 1)u^{(2)} = 0.$$

In result one obtains

$$u^{(2)} = A(\omega^2 - 1) \sum_{k=2}^{\infty} X_k^{(1)} \sin(kx) \cos(\omega_k^{(0)}\tau), \quad (24)$$

where: $\omega_k^{(0)} = \sqrt{k^2 + \omega^2 - 1}$.

Let us consider a second order approximation equation of the form

$$\begin{aligned}
u_{2\tau\tau} - u_{2xx} + (\omega^2 - 1)u_2 &= \\
&= \alpha_2 \omega^2 \sin x \cos(\omega\tau) + (\omega^2 - 1)(L_1 + L_2 + L_3),
\end{aligned} \tag{25}$$

where:

$$L_1 = (2 + \ln A)u_1^{(1)} - \alpha_1 u_{\tau\tau}^{(1)},$$

$$L_2 = 0.5u_0[\ln(u_0^2)]^2 + u^{(11)} \ln(\cos^2(\omega\tau)) + u^{(12)} \ln(\sin x),$$

$$L_3 = [2 + \ln(u_0^2)]u^{(2)} - \alpha_1 u_{\tau\tau}^{(2)} + u^{(11)} \ln(\sin^2 x) + u^{(12)} \ln(\cos^2(\omega\tau)).$$

The terms occurring in the right-hand side of the function L_1 do not include resonance harmonics. In contrary, in the function L_2 there occur, only resonance harmonic $\sin x \cos(\omega\tau)$. In the function L_3 , inspite of the already mentioned harmonic, there appears also the resonance of the form $\sin(kx) \cos \omega_k x$, $k = 2, 3, \dots$.

A proper choice of the constant α_2 allows for omitting $\sin x \cos(\omega\tau)$. In order to avoid problems concerning other resonance harmonics the following procedure can be applied.

The following change of variables is introduced

$$\omega_k = \omega_k^{(0)} + \beta_k^{(1)}\delta + \beta_k^{(2)}\delta^2 + \dots$$

and thus

$$\begin{aligned}
u^{(2)} &= A(\omega^2 - 1) \sum_{k=2}^{\infty} X_k \sin(kx) \cos(\omega_k^{(0)}\tau) + \\
&+ A(\omega^2 - 1)\delta \sum_{k=2}^{\infty} X_k \beta_k^{(1)} \sin(kx) \cos(\omega_k^{(0)}\tau).
\end{aligned}$$

Now, by a proper choice of the constant $\beta_k^{(1)}$ one can avoid all the resonance terms appearing in the right-hand side of equation (25).

4. Conclusions

As it has been shown, the small δ method can be applicable for construction of periodic solutions to nonlinear partial differential equations to the second approximation order.

Here only a construction of solution is presented. The problems of convergence, accuracy estimation, as well as construction of higher order approximation need further investigations.

5. References

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